# Cryptanalysis of RIPEMD-128/160 

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## What is a Hash Function?



- H maps an arbitrary length input (the message $M$ ) to a fixed length output (typically $n=128, n=160$ or $n=256$ ).
- no secret parameter.
- H must be easy to compute.

The security goals

## pre-image resistance:

given an output challenge $y$, the attacker can not find a message $x$ such that $H(x)=y$, in less than $\theta\left(2^{n}\right)$ operations.

2nd pre-image resistance:
given a challenge $(x, y)$ so that $H(x)=y$, the attacker can not find a message $x^{\prime} \neq x$ such that $H\left(x^{\prime}\right)=y$, in less than $\theta\left(2^{n}\right)$ operations.

## collision resistance:

the attacker can not find two messages ( $x, x^{\prime}$ ) such that $H(x)=H\left(x^{\prime}\right)$, in less than $\theta\left(2^{n / 2}\right)$ operations (a generic attack with the birthday paradox exists [Yuval-79]).


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And other ones: near collisions, multicollisions, random oracle look-alike, ...

## General construction

For historical reasons, most hash functions are composed of two elements:

- a compression function $h$ : a function for which the input and output size is fixed.
- a domain extension algorithm: an iterative process that uses the compression function $h$ so that the hash function $H$ can handle inputs of arbitrary length.


The Merkle-Damgård domain extension algorithm

The most famous domain extension algorithm used is called the Merkle-Damgård [Merkle Damgård-89] iterative algorithm.


## General design and security notions

- A collision on an iterated hash function $\mathcal{H}$ always comes from a collision on the compression function $h$ :

$$
\mathcal{H}(M)=\mathcal{H}\left(M^{*}\right) \Longrightarrow h(c v, m)=h\left(c v^{*}, m^{*}\right)
$$

## The conditions on $C v$ and $m$ give different kind of attacks :

Collision $c v=c v^{*}$ fixed and $m \neq m^{*}$ free.
Semi-free-start Collision $c v=c v^{*}$ and $m \neq m^{*}$ are free.
Free-start Collision $(c v, m) \neq\left(c v^{*}, m^{*}\right)$ are free.

The cryptanalysis history of MD5 is a good example of why (semi)-free-start collisions are a serious warning.

## Motivations to study RIPEMD

- MDx-like hash function is a very frequent design :

$$
\begin{aligned}
& 1990 \text { MDx (MD 4, MD } 5, \text { SHA-1, HAVAL, RIPEMD) } \\
& 2002 \text { SHA-2 (SHA-224, ..., SHA-512) }
\end{aligned}
$$

- Some old hash functions are still unbroken :

Broken MD 4, MD5, RIPEMD-0
Broken HAVAL
Broken SHA-1
Unbroken RIPEMD-128, RIPEMD-160
Unbroken SHA-2

- RIPEMD-128/ RIPEMD-160

Design 15 years old.
unbroken 9 years after Wang's attacks [WLF+05].

# Cryptanalysis of RIPEMD-128 

Thomas Peyrin<br>joint work with Franck Landelle

(accepted at Eurocrypt 2013)

## ChinaCrypt 2013

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technological
UNIVERSITY

## Results on RIPEMD-128 compression function

## RIPEMD-128 parameters:

## Digest 128 bits <br> Steps 64 steps (4 rounds of 16 steps each)

Known and new results on RIPEMD-128 compression function:

| Target | \#Steps | Complexity | Ref. |
| :---: | :---: | :---: | :---: |
| collision | 48 | $2^{40}$ | [MNS12] |
| collision | 60 | $2^{57.57}$ | new |
| collision | 63 | $2^{59.91}$ | new |
| collision | Full | $2^{61.57}$ | new |
| non-randomness | 52 | $2^{107}$ | [SW12] |
| non-randomness | Full | $2^{59.57}$ | new |

## In this talk

Function RIPEMD-128 compression function

Attack a semi-free-start collision
Find $c v, m \neq m^{*} / h(c v, m)=h\left(c v, m^{*}\right)$.
Strategy - Choose a message difference $\delta_{m}=m \oplus m^{*}$ $\rightarrow$ new message difference used

- Find a differential path on all intermediate state variables
$\rightarrow$ new type of differential path with two non-linear parts
- Find conforming $c v$ and $m$
$\rightarrow$ new branch merging technique for collision search


## Outline

Description of RIPEMD-128

Finding a differential path
Finding a message difference
Finding the non-linear part

Finding a conforming pair
Generating a starting point
Merging the 2 branches

Conclusion

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A compression function

$$
m=m_{0}\left\|m_{1}\right\| \cdots \| m_{15}
$$

Message block $m$


## Compression Function

## Overview of RIPEMD-128 compression function



The step function

$$
W_{i}^{r}=m_{\pi_{j}^{r}(i)}
$$



Left Branch - step $i$, round $j$

$$
W_{i}^{\ell}=m_{\pi_{j}^{\ell}(i)}
$$



Right Branch - step $i$, round $j$

The boolean functions

## Boolean functions in RIPEMD-128:

- $\operatorname{XOR}(x, y, z):=x \oplus y \oplus z$,
- $\operatorname{IF}(x, y, z):=x \wedge y \oplus \bar{x} \wedge z$
- $\operatorname{ONX}(x, y, z):=(x \vee \bar{y}) \oplus z$

| Steps $i$ | Round $j$ | $\phi_{j}^{\ell}(x, y, z)$ | $\phi_{j}^{r}(x, y, z)$ |
| :---: | :---: | :---: | :---: |
| 0 to 15 | 0 | $\operatorname{XOR}(x, y, z)$ | $\operatorname{IF}(z, x, y)$ |
| 16 to 31 | 1 | $\operatorname{IF}(x, y, z)$ | $\operatorname{ONX}(x, y, z)$ |
| 32 to 47 | 2 | $\operatorname{ONX}(x, y, z)$ | $\operatorname{IF}(x, y, z)$ |
| 48 to 63 | 3 | $\operatorname{IF}(z, x, y)$ | $\operatorname{XOR}(x, y, z)$ |

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## The classical strategy (example SHA-1)

1. Find a message difference $\delta_{m}$ and a differential path with high probability on the middle and last steps (ideally after the first round).
2. Find a "realistic" non-linear differential path on the first steps (ideally on the first round for a semi-free-start collision).
3. Find a chaining variable $c v$ and a message $m$ such that the state differential path is followed (use special freedom degrees tricks like neutral bits, message modification, boomerangs, etc.).


The classical strategy (example RIPEMD-128)

1. Find a message difference $\delta_{m}$ and a differential path with high probability on the middle and last steps for both branches.
2. Find a "realistic" non-linear differential path on the first steps.
3. Find a conforming chaining variable $c v$ and a message $m$.


## What shape should have the differential path ?

## Boolean functions can help to control the diff. propagation.

## Properties of the boolean functions:

- XOR : no control of differential propagation
- ONX: some control of differential propagation and permits low diffusion.
- IF : a good control of differential propagation and permits no diffusion.

| Steps $i$ | Round $j$ | $\phi_{j}^{\prime}(x, y, z)$ | $\phi_{j}^{r}(x, y, z)$ |
| :---: | :---: | :---: | :---: |
| 0 to 15 | 0 | $\operatorname{XOR}(x, y, z)$ | $\operatorname{IF}(z, x, y)$ |
| 16 to 31 | 1 | $\operatorname{IF}(x, y, z)$ | $\operatorname{ONX}(x, y, z)$ |
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Choosing the message block difference
Goals keep low ham. weight on the expanded message block Choice Put a difference on a single word of message


With the message block difference on $m_{14}$ :

- "no difference" on rounds with XOR function.
- Non-linear differential paths are in the round with IF

Choosing the message block difference
$m_{14}$ is really "magic" with regards to our criteria.

However, how to handle these two non-linear parts which are in different branches, and not in the first round?


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Automatic tool on generalized conditions
We implemented a tool similar to [CR06] for SHA-1 that uses generalized conditions.

| Hexa | $\left(b, b^{*}\right)$ <br> Notation | $(0,0)$ | $(1,0)$ | $(0,1)$ | $(1,1)$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0xF | $?$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| 0x9 | - | $\checkmark$ |  |  | $\checkmark$ |
| 0x6 | x |  | $\checkmark$ | $\checkmark$ |  |
| 0x1 | 0 | $\checkmark$ |  |  |  |
| $0 \times 2$ | u |  | $\checkmark$ |  |  |
| $0 \times 4$ | n |  |  | $\checkmark$ |  |
| $0 \times 8$ | 1 |  |  |  | $\checkmark$ |

## Where

- $b$ : a bit during the treatment the message $m$
- $b^{*}$ : the same bit for the second message $m^{*}$.

Finding a differential path 000000000

## Left branch

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35: -------------------------------10
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## Left branch

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| 18: | 1111 |
| 19: | - n |
| 20: - | -0 |
| 21: | - 1 |
| 22 : | -u |
| $23:$ | -- -0 |
| 24: | -n-1 |
| 25 : | -0- |
| $26:$ | -1 |
| 27: 1 | -u- |
| 28: 0 | -0 |
| 29: n | 1 |
| 30: u |  |
| 31: u |  |
| 32: 1 |  |
| $33:$ |  |
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28: 0------10x9
1 29: n-u-30: u-31:32: 1x-14

## Right branch

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## Right branch



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## Outline

## Description of RIPEMD-128

Finding a differential path Finding a message difference Finding the non-linear part

Finding a conforming pair
Generating a starting point
Merging the 2 branches

## Conclusion

Following a classical differential path
A classical collision search is composed of two subparts:
step 1 handling the low-probability non-linear parts using the message block freedom
step 2 the remaining steps in both branches are verified probabilistically


Finding a conforming pair


Our collision search is composed of three subparts:
step 1 Satisfy the two non-linear parts using the freedom from both branches internal states and a few message words
step 2 From this starting point, merge the two branches using some remaining free message words
step 3 Handle probabilistically the linear part in both branches

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Satisfying the two non-linear parts simultaneously (step 1)


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step 1 Satisfy the two non-linear parts using the freedom from both branches internal states and a few message words
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Handling probabilistically the linear parts (step 3)
Probabilities of the linear parts are fixed after the first step:

- The probability of the left branch is $2^{-15}$.
- The probability of the right branch is $2^{-14.32}$.
- one extra bit condition in order to get a collision when adding the two branches
- $\rightarrow$ The overall probability for collision is $2^{-30.32}$.
(these probabilities have been verified experimentally)
Our collision search is composed of three subparts:

step 3 Handle probabilistically the linear part in both branches

$\rightarrow$ we need to obtain $2^{30.32}$ solutions of the merging system
Our collision search is composed of three subparts:

step 3 Handle probabilistically the linear part in both branches


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Merging the two branches (step 2)


Our collision search is composed of three subparts:
step 2 From this starting point, merge the two branches using some remaining free message words

The starting point


## What is fixed ?

Message $m_{12}, m_{3}, m_{10}, m_{1}, m_{8}, m_{15}, m_{6}, m_{13}, m_{4}, m_{11}, m_{7}$.
Left State $\left(X_{12}, \ldots, X_{24}\right)$
Right State $\left(Y_{3}, Y_{4}, \ldots, Y_{14}\right)$.
What is free ?
Message $m_{0}, m_{2}, m_{5}, m_{9}, m_{14}$.

## Prepare the merging system

## The system is quite complex:



The probability that a random choice of $m_{0}, m_{2}, m_{5}, m_{9}, m_{14}$ gives a solution is
$2^{-128}$

## Reducing the merging system

- in the search for a starting point (step 1), we chose $m_{11}$ such that: $Y_{3}=Y_{4}$
- randomly chose a $m_{14}$ value and deduce $m_{9}$ such that: $X_{5}^{\gg 5} \boxminus m_{4}=0 \mathrm{xffffffff}$
$\rightarrow$ the system becomes much simpler and represents less steps of the compression function.


Solving the merging system
The goal now is to find $m_{0}, m_{2}, m_{5}$ such that

$$
X_{i}=Y_{i} \text { for } i \in\{-3,-2,-1,0\}
$$

|  | $X_{0}$ | $Y_{0}$ | $X_{-1}$ | $Y_{-1}$ | $X_{-2}$ | $Y_{-2}$ | $X_{-3}$ | $Y_{-3}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $m_{2}$ |  | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| $m_{0}$ | $\checkmark$ |  |  |  |  | $\checkmark$ |  |  |
| $m_{5}$ |  |  |  |  | $\checkmark$ |  | $\checkmark$ | $\checkmark$ |

To solve the merging system:

1. find a value of $m_{2}$ that verifies $X_{-1}=Y_{-1}$
2. deduce $m_{0}$ to fulfill $X_{0}=Y_{0}$
3. obtain $m_{5}$ to satisfy a combination of $X_{-2}=Y_{-2}$ and
4. finally the $4^{\text {th }}$ equation is verified with probability $2^{-32}$

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|  | $X_{0}$ | $Y_{0}$ | $X_{-1}$ | $Y_{-1}$ | $X_{-2}$ | $Y_{-2}$ | $X_{-3}$ | $Y_{-3}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $m_{2}$ |  | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| $m_{0}$ | $\checkmark$ |  |  |  |  | $\checkmark$ |  |  |
| $m_{5}$ |  |  |  |  | $\checkmark$ |  | $\checkmark$ | $\checkmark$ |

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| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $m_{2}$ |  | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| $m_{0}$ | $\checkmark$ |  |  |  |  | $\checkmark$ |  |  |
| $m_{5}$ |  |  |  |  | $\checkmark$ |  | $\checkmark$ | $\checkmark$ |

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| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $m_{2}$ |  | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| $m_{0}$ | $\checkmark$ |  |  |  |  | $\checkmark$ |  |  |
| $m_{5}$ |  |  |  | $\checkmark$ |  | $\checkmark$ | $\checkmark$ |  |

To solve the merging system:

1. find a value of $m_{2}$ that verifies $X_{-1}=Y_{-1}$
2. deduce $m_{0}$ to fulfill $X_{0}=Y_{0}$
3. obtain $m_{5}$ to satisfy a combination of $X_{-2}=Y_{-2}$ and $X_{-3}=Y_{-3}$

## Solving the merging system

The goal now is to find $m_{0}, m_{2}, m_{5}$ such that

$$
X_{i}=Y_{i} \text { for } i \in\{-3,-2,-1,0\}
$$

|  | $X_{0}$ | $Y_{0}$ | $X_{-1}$ | $Y_{-1}$ | $X_{-2}$ | $Y_{-2}$ | $X_{-3}$ | $Y_{-3}$ |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $m_{2}$ |  | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| $m_{0}$ | $\checkmark$ |  |  |  |  | $\checkmark$ |  |  |
| $m_{5}$ |  |  |  |  | $\checkmark$ |  | $\checkmark$ | $\checkmark$ |

To solve the merging system:

1. find a value of $m_{2}$ that verifies $X_{-1}=Y_{-1}$
2. deduce $m_{0}$ to fulfill $X_{0}=Y_{0}$
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4. finally the $4^{\text {th }}$ equation is verified with probability $2^{-32}$

Complexity of the semi-free-start collision attack

- Solving the merging system costs 19 RIPEMD-128 step computations (19/128 of the compression function cost).
- The probability of success of the merging is $2^{-34}$ (because of $4^{\text {th }}$ equation and 2 extra hidden bit conditions)
- We need to find $2^{30.32}$ solutions of the merging system.

The total complexity is therefore

$$
19 / 128 \times 2^{34} \times 2^{30.32} \simeq 2^{61.57}
$$

calls to the compression function.

## Outline

## Description of RIPEMD-128

Finding a differential path
Finding a message difference
Finding the non-linear part

Finding a conforming pair
Generating a starting point
Merging the 2 branches

Conclusion

## Conclusion

## This work:

- a new cryptanalysis technique for parallel branches based functions
- a collision attack on the full compression function of RIPEMD-128
- a distinguisher on the hash function of RIPEMD-128
- a LOT of details (many not described here)


## Perspectives:

- improvements of this technique
- an example of collision for RIPEMD-128?
- apply to other 2-branch hash functions
- what about RIPEMD-160?


## Cryptanalysis of RIPEMD-160

## Thomas Peyrin

joint work with F. Mendel, M. Schläffer, L. Wang and S. Wu
(accepted at Asiacrypt 2013)

## ChinaCrypt 2013

Fuzhou, China - October 25, 2013


Results on RIPEMD-160 compression function

## RIPEMD-160 parameters:

Digest 160 bits
Steps 80 steps (5 rounds of 16 steps each)

Known and new results on RIPEMD-160 compression function:

| Target | \#Steps | Complexity | Ref. |
| :---: | :---: | :---: | :---: | :---: |
| semi-free-start collision | 36 | low (practical) | [MNS12] |
| 1 <br> st <br> round |  |  |  |
| semi-free-start collision | $\mathbf{3 6}$ | $2^{70.4}$ | new |
| semi-free-start collision | $\mathbf{4 2}$ | $2^{75.5}$ | new |

```
RIPEMD-160 >> RIPEMD-128
```


## Why are the improvements far less impressive for

RIPEMD-160?

The technique we applied on RIPEMD-128 is much harder to apply on RIPEMD-160:

- finding non-linear parts is more difficult than for RIPEMD-128
- evaluating the probability of a differential path is hard (because two additions are interlinked)
- ... so more complicated to have a global view of what will and what won't work when trying to organize the attack

On top of that, RIPEMD-160 has

- better diffusion (impossible to force no diffusion, even in IF rounds)
- more steps ...


## Thank you for your attention!

We are looking for good PhD students in symmetric key crypto.
If interested, please contact me at: thomas.peyrin@ntu.edu.sg


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