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# The Window Heuristic: Automating Differential Trail Search in ARX Ciphers with Partial Linearization Trade-offs

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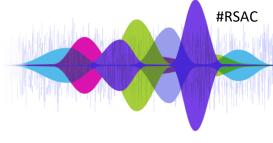


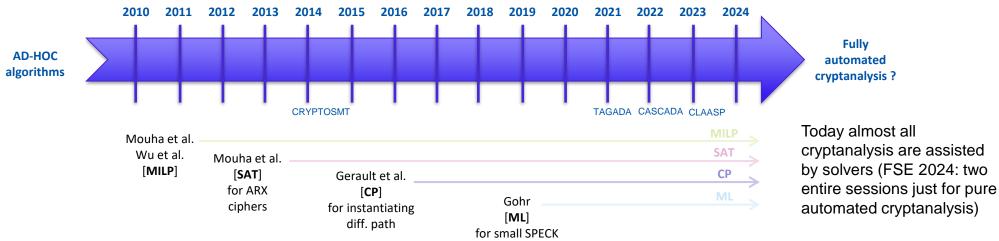


# **Automated Cryptanalysis**



# **Timeline of Automated Cryptanalysis**





**Automated cryptanalysis** using declarative frameworks (SAT/MILP/CP/etc.) is generally slower or at best same as ad-hoc tools, but so much **more convenient** 

Mainly on **differential** and **linear cryptanalysis**, but now also on integral distinguishers, cube attacks, meetin-the-middle attacks, etc.

**Solving time** is a crucial aspect and can be impacted by:

- the framework you use (SAT/MILP/CP/etc.)
- the strategy of modeling

- the solver
- the type of problem studied / scale





# **Automated Cryptanalysis for Differential Paths**

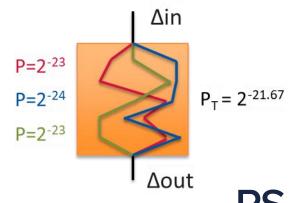


#### Typically, for finding differentials or differential trails:

- Use variables to represent the various stages of the internal state bit differences during the round (and throughout the rounds)
- Use other variables to represent the probability P of the differential path (in -log2)
- Model a round of the cipher as a set of declarative constraints (Markov assumption!) to represent the
  difference propagation (either truncated or not). Use temporary variables if needed for certain
  components.
- Put all this into a system and use a solver on it.
- Can be combined with extra upper-level strategies (Matsui branch-and-bound, etc.)

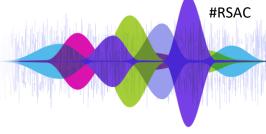
#### One can:

- Find the best differential path / linear characteristic
- Enumerate the number of solutions
- Estimate the probability of a differential





# Satisfiability Problem (SAT/SMT) for Cryptanalysis



All variables are Boolean, a constraint is a Conjunctive Normal Form (CNF – conjunction of disjunctions/clauses). Ex: (avb)  $\land$  (¬avcvd)  $\land$  (¬bvc)

- **Equality** is easy to model  $x = y \Leftrightarrow (\neg x \lor y) \land (x \lor \neg y) = 1$
- Linear layers are easy to model, by combining the simple XOR model:
   x = a ⊕ b ⇔ (¬a ∨ b ∨ x) ∧ (a ∨ ¬b ∨ x) ∧ (a ∨ b ∨ ¬x) ∧ (¬a ∨ ¬b ∨ ¬x) = 1 (use dummy variables with combinations of XORs for multiple-inputs XORs)
- Nonlinear layers (Sbox/AND/OR/Additions) are more complex to model

Then, add a constraint to force the path to have a certain fixed probability P:

- If the solver returns SAT, we directly get a path with probability P.
- If the solver returns UNSAT, we run again this time with a probability P' < P (drawback: we need to iterate through decreasing target values).

SAT is very good for all ciphers, especially for ARX ciphers
SAT is very good for finding optimal differential paths, and
good for estimating the probability of a differential.





#### Mixed Integer Linear Programming (MILP) for Cryptanalysis



All variables are Boolean/integer/real, a constraint is a linear inequality

Ex: 
$$\{a + 4b + 2c \ge 3d + 7e\}$$

- **Equality** is easy to model  $x = y \Leftrightarrow \{x \ge y\}, \{y \ge x\}$
- Linear layers are easy to model, by using 4 inequalities:  $x = a \oplus b \Leftrightarrow \{a + b \ge x\}, \{a + x \ge b\}, \{b + x \ge a\}, \{a + b + x \le 2\}$  (use dummy variables with combinations of XORs for multiple-inputs XORs)
- Nonlinear layers (Sbox/AND/OR/Additions) are more complex to model

Then, add an **objective function** to minimize/maximize (encoding the path probability). Ex: {a + 3b + 2c + 5d}. The solver will directly return the best instance identified.



MILP is **good** on **most ciphers**.

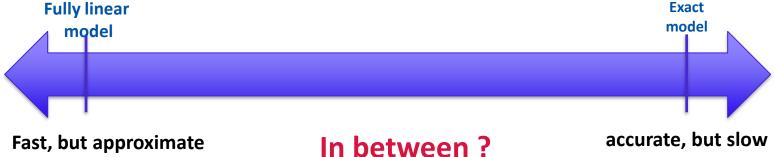
MILP is very good for finding optimal differential paths, less so for estimating the probability of a differential.



# The Problem with Modular Addition Modeling



- Sboxes are relatively easy to model: transform DDT into constraints
- You can't use that strategy for ARX: size is too large (32/64 bits)
- To overcome this, researchers tried:
  - to **fully linearise** mod. addition (Ex: MDx/SHA-x collision attacks):  $x = a \oplus b \approx a \oplus b$
  - to use Lipmaa-Moriai formula for XOR-differential propagation through addition: for  $(\alpha, \beta \rightarrow \gamma)$ : eq $(\alpha \ll 1, \beta \ll 1, \gamma \ll 1) \land (\alpha \oplus \beta \oplus \gamma \oplus (\beta \ll 1)) = 0$ , with eq $(x, y, z) := (\neg x \oplus y) \land (\neg x \oplus z)$
  - to build the differential path iteratively, only propagating the most likely differences at each round (not representing the full cipher in a single model): partial DDT (pDDT)



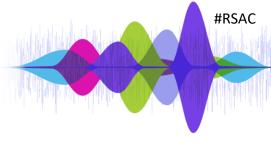




# **The Window Heuristic**



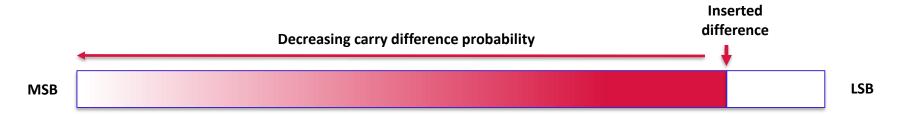
# The Windows Heuristic Idea



A difference on bit i of a modular addition input can create a differential carry propagation from i to many later positions.

A linear model forces 0 carry difference propagation (but is fast), while exact model allows any propagation (but is slow).

 Our observation: good differential paths are (almost always) composed of modular addition diff. transitions that are propagating very little (if not at all), with only a few rounds with more propagation.







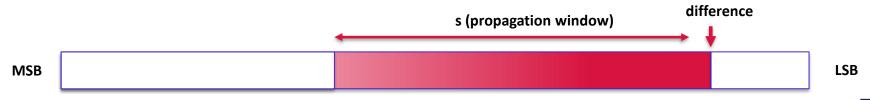
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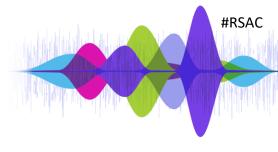
- Our observation: good differential paths are (almost always) composed of modular addition diff. transitions that are propagating very little (if not at all), with only a few rounds with more propagation.
- Our idea: generalize the linear and exact models, by allowing a difference in the carry to propagate a little bit (over s bits, aka the "window" of propagation). We can control for each modular addition and each difference bit of it, what window size to allow.







# The Windows Heuristic Idea



#### **Example:**

Difference 0x080000001e4a0848



Difference 0x08000000000e0808



Difference 0x0000000f2400040

Carry Difference 0x0000000ec040000







# **Encoding the Window in MILP and SAT**



 In MILP, for each n-bit modular addition with s-bit window, we add the (n - 1 - s) following new constraints on the corresponding carry C:

$$\sum_{i=1}^{s+1} C[j-i] \le s, \quad \text{for all } j \in [s+1, ..., n-1].$$

• In SAT, for each n-bit modular addition with s-bit window, we add the  $2^{2(s+1)}$  (n - 1 - s) following new constraints on the corresponding carry C:

$$\bigwedge_{j=s+1}^{n-1} \bigvee_{j=1}^{s+1} \neg (a[j-i] \oplus b[j-i] \oplus c[j-i])$$





# **The Heuristics**



Window Heuristic does not create invalid paths, but potentially miss good ones (good to find attacks, bad to prove the non-existence of diff. paths).

We observed that **fixing s for an entire round** generally works well in practice, but this remains dependent on the cipher and attack we study.

#### Other possible heuristics:

- Force each round to contain few consecutive carry difference clusters (in general small for good differential paths)
- Restrict the total number of carry differences for each modular additions (in general not too large for good differential paths)

Unfortunately, these other heuristics did not improve the results.



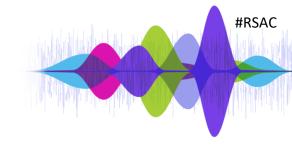




# Results



# **Application to SPECK Block Cipher**



Version	Rounds	$\log_2(P_{DK})$	$\log_2(P_D)$	$\log_2(P_K)$	Ref.
	15	-94.0	-32.0	-62.0	[42]
SPECK-32/64	15	-85.0	-32.0	-53.0	[41]
	15	-73.0	-31.0	-42.0	$w_s = 0$
	14	-68.0	-43.0	-25.0	[42]
	14	-66.6	-43.0	-23.6	[41]
	14	-65.0	-34.0	-31.0	$w_s = 0$
SPECK-48/96	15	-89.0	-46.0	-43.0	[42]
	15	-83.5	-42.0	-41.5	[41]
	15	-75.0	-41.0	-34.0	$w_s = 0$
	16	-86.0	-43.0	-43.0	$w_s = 0$
	14	-88.0	-37.0	-51.0	[42]
	14	-72.0	-35.0	-37.0	[41]
	14	-66.0	-32.0	-34.0	$w_s = 0$
	15	-105.0	-45.0	-60.0	[42]
SPECK-64/128	15	-89.0	-42.0	-47.0	[41]
SFECK-04/120	15	-76.0	-33.0	-43.0	$w_s = 0$
	16	-103.0	-60.0	-43.0	[42]
	16	-85.0	-39.0	-46.0	$w_s = 0$
	17	-112.0	-62.0	-50.0	[42]
	16	-121.0	-76.0	-45.0	[42]
SPECK-128/256	16	-96.0	-52.0	-44.0	$w_s = 0$
DFEOV-170/520	19	-190.0	-111.0	-79.0	[42]
	19	-171.0	-102.0	-69.0	$w_s = 0$

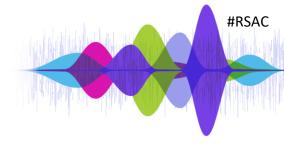
[41] Qin et al. CoRR abs/2203.09741 - 2022

[42] Sadeghi et al.
Des. Codes Cryptography 2021





# **Application to ChaCha**



#### Differential paths on ChaCha - comparison

Number	MILP +				SAT + window heuristic + "full window size"	MILP	S-function
of	winde	ow heur.		[7]	[7]		
rounds	Pr	$w_s$	Pr	Pr	Pr		
1	3	3	3	3	3		
2	37	3	37	37	37		
3	120	1	120	147	157		
4	218	1	217	316	349		

[7] Bellini et al. - IJACT 2023

# Differential paths on ChaCha with MILP

	Single-key				
$\mathbf{r}$	no-condition		condi	tions	
	Time	Pr	Time	Pr	
1	2.17s	3	1.62s	3	
2	13.2s	37	3.30s	37(0)	
3	13.6s	147	319s	120(0)	
4	36728s	316	48745s	218(1)	

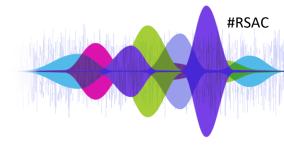
#### **Boomerang Distinguishers on ChaCha**

Number	Theoretical	Experimental
of rounds	probability	probability
2	$2^{-6}$ ( $w_s = -1$ , bottom part starting round 2)	$2^{-0.05}$
3	$2^{-10}$ ( $w_s = -1$ , bottom part starting round 2)	$2^{-1.41}$
4	$2^{-90}$ ( $w_s = 0$ , bottom part starting round 3)	+
5	$2^{-154}$ ( $w_s = 1$ , bottom part starting round 3)	=
6	$2^{-228}$ ( $w_s = 1$ , bottom part starting round 3)	-





# **Application to LEA Block Cipher**



#### **Differential paths on LEA**

	Window		Others			
$\mathbf{r}$	siz	ze				
	Pr	$w_s$	Pr	Ref.	Pr	Ref.
12	107	9	112	[43]	107	[3]
13	123	1	134	[43]	127	[3]

<sup>[3]</sup> Bagherzadeh et al. - IET Information Sec. 2020

#### Differential paths on LEA (time)

	Single-key					
$\mathbf{r}$	no-cor	$\mathbf{dition}$	conditions			
	Time	Pr	Time	Pr		
12	100709s	107/(-1)	73405s	107/(9)		
13	609.53s	143/(-1)	7985s	123/(1)		

#### **Key recovery on LEA**

Distinguisher			Key recovery		
Rounds	Pr	Ref.	Rounds	Complexity	Ref.
13	$2^{-123.79}$	[43]	14	$2^{124.79}$	[43]
13	$2^{-110.97}$	Ours $(w_s = 1)$	14	$2^{111.97}$	Ours $(w_s = 1)$





<sup>[43]</sup> Song et al. - ACISP 2016

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# Conclusion

**Future Works** 



# Conclusion



- Maybe better heuristics exist with such window modeling trick
- Generalize the way we limit the carry, maybe other good representations are possible
- Generalize to more complex operations cases (multiplications, algebraic formula, ..)
- What about linear cryptanalysis? Truncated differential cryptanalysis?
- Incorporate the Window Heuristic into larger models with key recovery





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